Chapter 12: Indexing and Hashing



- Basic Concepts
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- B-Tree Index Files
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- Comparison of Ordered Indexing and Hashing
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Basic Concepts



- Indexing mechanisms used to speed up access to desired data.
 - E.g., author catalog in library
- Search Key attribute or set of attributes used to look up records in a file.
- An index file consists of records (called index entries) of the form

search-key pointer

- Index files are typically much smaller than the original file
- Two basic kinds of indices:
 - Ordered indices: search keys are stored in sorted order
 - Hash indices: search keys are distributed uniformly across "buckets" using a "hash function".

Index Evaluation Metrics



* Access types supported efficiently. E.g.,

- records with a specified value in the attribute
- or records with an attribute value falling in a specified range of values.

Indexing techniques evaluated on basis of:

- Access time
- Insertion time
- Deletion time
- Space overhead

Ordered Indices



- In an ordered index, index entries are stored sorted on the search key value. E.g., author catalog in library.
- Primary index: in a sequentially ordered file, the index whose search key specifies the sequential order of the file.
 - Also called clustering index /* Not! */
 - The search key of a primary index is usually but not necessarily the primary key.
- Secondary index: an index whose search key specifies an order different from the sequential order of the file. Also called

non-clustering index. /* Wrong Again! */

 Index-sequential file: ordered sequential file with a primary index.

Dense Index Files



Dense index — Index record appears for every search-key value in the file.

Brighton		A-217	Brighton	750	
Downtown		Δ_101	Downtown	500	
Downtown		A-101	Downtown	500	
Mianus		A-110	Downtown	600	5
Perryridge		A-215	Mianus	700	
Redwood		A-102	Perryridge	400	\square
Round Hill		A-201	Perryridge	900	\square
·	_ / /	A-218	Perryridge	700	
		A-222	Redwood	700	
		A-305	Round Hill	350	
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Sparse Index Files



- Sparse Index: contains index records for only some search-key values.
 - Applicable when records are sequentially ordered on searchkey
- * To locate a record with search-key value *K* we:
 - Find index record with largest search-key value < *K*
 - Search file sequentially starting at the record to which the index record points
- Less space and less maintenance overhead for insertions and deletions.
- Generally slower than dense index for locating records.
- Good tradeoff: sparse index with an index entry for every block in file, corresponding to least search-key value in the block.

Example of Sparse Index Files



Brighton		A-217	Brighton	750	
Mianus		A-101	Downtown	500	
Redwood		A-110	Downtown	600	
		A-215	Mianus	700	
		A-102	Perryridge	400	\square
		A-201	Perryridge	900	\square
		A-218	Perryridge	700	
	×	A-222	Redwood	700	
		A-305	Round Hill	350	

Multilevel Index



- If primary index does not fit in memory, access becomes expensive.
- To reduce number of disk accesses to index records, treat primary index kept on disk as a sequential file and construct a sparse index on it.
 - outer index a sparse index of primary index
 - inner index the primary index file
- If even outer index is too large to fit in main memory, yet another level of index can be created, and so on.
- Indices at all levels must be updated on insertion or deletion from the file.

Multilevel Index (Cont.)





Index Update: Deletion



- If deleted record was the only record in the file with its particular search-key value, the search-key is deleted from the index also.
- Single-level index deletion:
 - Dense indices deletion of search-key is similar to file record deletion.
 - Sparse indices if an entry for the search key exists in the index, it is deleted by replacing the entry in the index with the next search-key value in the file (in search-key order). If the next search-key value already has an index entry, the entry is deleted instead of being replaced.

Index Update: Insertion



Single-level index insertion:

- Perform a lookup using the search-key value appearing in the record to be inserted.
- Dense indices if the search-key value does not appear in the index, insert it.
- Sparse indices if index stores an entry for each block of the file, no change needs to be made to the index unless a new block is created. In this case, the first search-key value appearing in the new block is inserted into the index.
- Multilevel insertion (as well as deletion) algorithms are simple extensions of the single-level algorithms

Secondary Indices



- Frequently, one wants to find all the records whose values in a certain field (which is not the search-key of the primary index satisfy some condition.
 - Example 1: In the *account* database stored sequentially by account number, we may want to find all accounts in a particular branch
 - Example 2: as above, but where we want to find all accounts with a specified balance or range of balances
- We can have a secondary index with an index record for each search-key value; index record points to a bucket that contains pointers to all the actual records with that particular search-key value.



Secondary Index on **balance** field of **account**



Primary and Secondary Indices



- Secondary indices have to be dense.
- Indices offer substantial benefits when searching for records.
- When a file is modified, every index on the file must be updated, Updating indices imposes overhead on database modification.
- Sequential scan using primary index is efficient, but a sequential scan using a secondary index is expensive
 - each record access may fetch a new block from disk

B+-*Tree Index Files*



B+-tree indices are an alternative to indexed-sequential files.

- Disadvantage of indexed-sequential files: performance degrades as file grows, since many overflow blocks get created. Periodic reorganization of entire file is required.
- Advantage of B⁺-tree index files: automatically reorganizes itself with small, local, changes, in the face of insertions and deletions. Reorganization of entire file is not required to maintain performance.
- Disadvantage of B⁺-trees: extra insertion and deletion overhead, space overhead.
- Advantages of B⁺-trees outweigh disadvantages, and they are used extensively.

B+-Tree Index Files (Cont.)



A B+-tree is a rooted tree satisfying the following properties:

- All paths from root to leaf are of the same length
- Each node that is not a root or a leaf has between [n/2] and n children.
- ✤ A leaf node has between [(n-1)/2] and n-1 values
- Special cases:
 - If the root is not a leaf, it has at least 2 children.
 - If the root is a leaf (that is, there are no other nodes in the tree), it can have between 0 and (*n*−1) values.

B+-*Tree Node Structure*



Typical node



- K_i are the search-key values
- P_i are pointers to children (for non-leaf nodes) or pointers to records or buckets of records (for leaf nodes).

* The search-keys in a node are ordered $K_1 < K_2 < K_3 < \ldots < K_{n-1}$

Leaf Nodes in B+-Trees

Properties of a leaf node:

- For i = 1, 2, ..., n–1, pointer P_i either points to a file record with search-key value K_i, or to a bucket of pointers to file records, each record having search-key value K_i. Only need bucket structure if search-key does not form a primary key. /* if not primary index! */
- ✤ If L_i , L_j are leaf nodes and i < j, L'_i 's search-key values are less than L'_i 's search-key values



✤ P_n points to next leaf node in search-key order



Non-Leaf Nodes in B+-Trees



- Non leaf nodes form a multi-level sparse index on the leaf nodes. For a non-leaf node with *m* pointers:
 - All the search-keys in the subtree to which P₁ points are less than K₁
 - For 2 ≤ *i* ≤ *n* − 1 /* n */, all the search-keys in the subtree to which *P_i* points have values greater than or equal to *K_{i-1}* and less than *K_{m-1}* /* K_i except for i=n */,



B+-tree for *account* file (n = 3)

Example of B+*-tree*





B+-tree for *account* file (n = 5)

- ★ Leaf nodes must have between 2 and 4 values $(\lceil (n-1)/2 \rceil$ and n-1, with n = 5).
- Non-leaf nodes other than root must have between 3 and 5 children (⌈(n/2⌉ and n with n =5).
- Root must have at least 2 children.

Observations about B+-trees



- Since the inter-node connections are done by pointers, "logically" close blocks need not be "physically" close.
- The non-leaf levels of the B⁺-tree form a hierarchy of sparse indices.
- The B⁺-tree contains a relatively small number of levels (logarithmic in the size of the main file), thus searches can be conducted efficiently.
- Insertions and deletions to the main file can be handled efficiently, as the index can be restructured in logarithmic time (as we shall see).