

3D Human Body Tracking

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Research Goal

Recognize body motion and gestures for multimodal interactions

A markerless, accurate body motion estimation

Research Approach

Use of an articulated human model for constraining the physical structure of the human body and its movement.

Particle filter-based tracking:

- Integrate particle filter with analytical inference techniques: detection of body parts: head, hands and torso.
- Infer analytically a subset of state parameters:
 - · Reducing the degree of freedom
 - · Automatic model initialization.

□ Estimate unknown static parameters (i.e. height and shape) during tracking, using mixture Gaussians approach.



Particle Filtering with Inference

Role in IMSC

User-state assessment from multimodal data

- Enabling technology for multimodal interactions
 An alternative non-invasive human motion capture technology.
 - Understanding of human body structure and human movement.

Uniqueness & Related Work

Recent works focused on improving efficiency using variance analysis, simulated annealing approach, partitioned sampling or hybrid Monte Carlo approach.
 Open problems:

- large dimensional state space,
- automatic initialization,
- robustness of tracking.
- Contributions of this project:

Improved tracking efficiency and robustness.

Automatic initialization of body pose

•Automatic estimation of human body shape: fitting the model to user's body proportions.



Tracking result

Accomplishments					5 Year Plan			
Recent Publications					□Improving the accuracy of the model for complex			
1. ((Cohen, M. L Immersive Ir Workshop o Objects Palr November, 2	ee, "3D Body Re nteraction", Seco n Articulated Mot na de Mallorca, § 2002.	construction nd Internation and De Spain, 21-2	on for tional eformable 23	 Automatic gesture recognition from the spatio- temporal changes of the articulated model Automatic assessment of user state from its body language 			
2. [Mun Wai Le 'Particle Filt Human Body Video Comp	e, Isaac Cohen, s er with Analytical y Tracking" Work outing, 2002, pp.	Soon Ki Ju Inference shop on N 159-165.	ing, for lotion and	Extends the framework for tracking multiple interacting persons.			
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