

Real-time 3D Face Tracking and Modeling From a Webcam



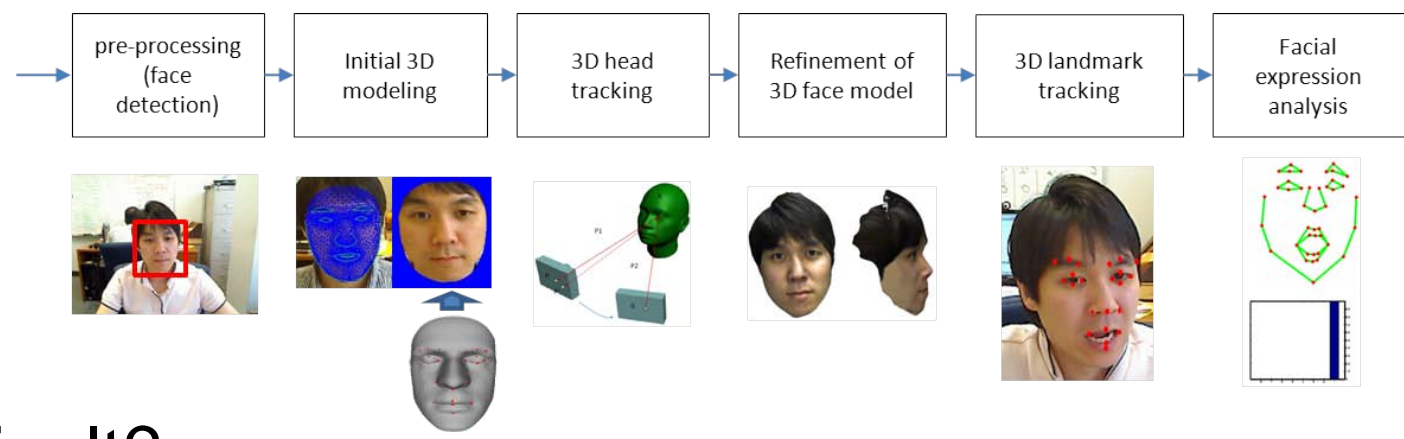
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Introduction

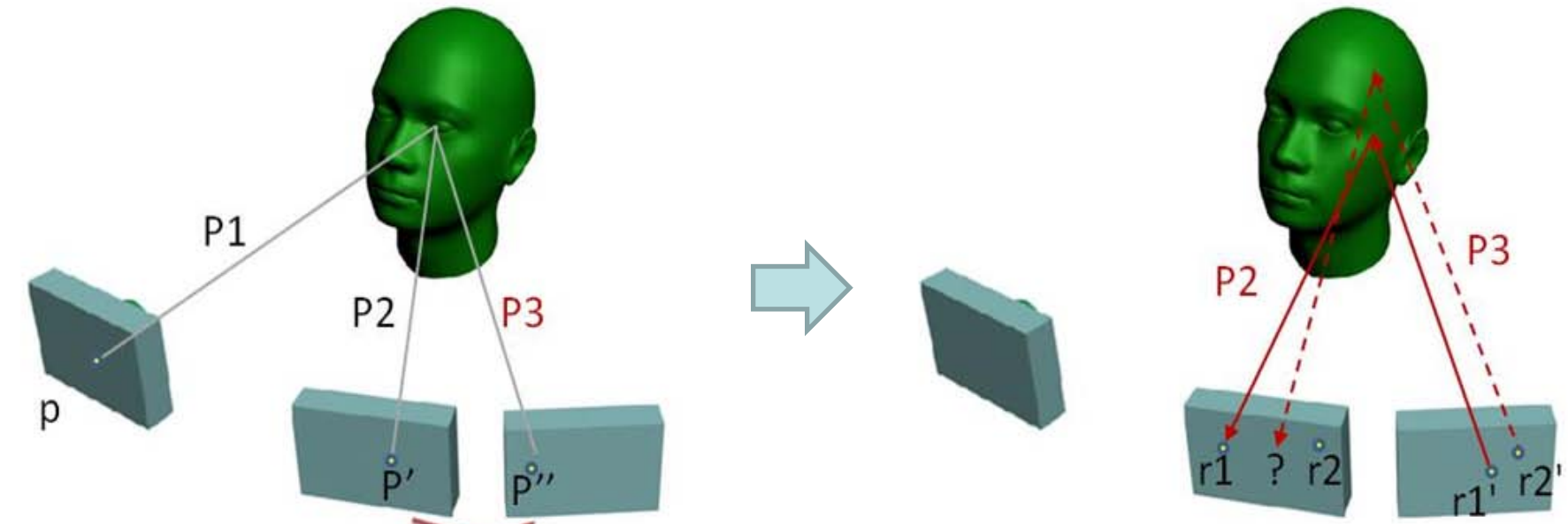
- Input: video from webcam
- Output: 3D (6dof) pose of face



- Why difficult?
 - (self-)occlusion, outliers, expressions, ...
- Key idea
 - Build 3D face model and use it for tracking

Adding new keypoints

- To handle wide pose angles



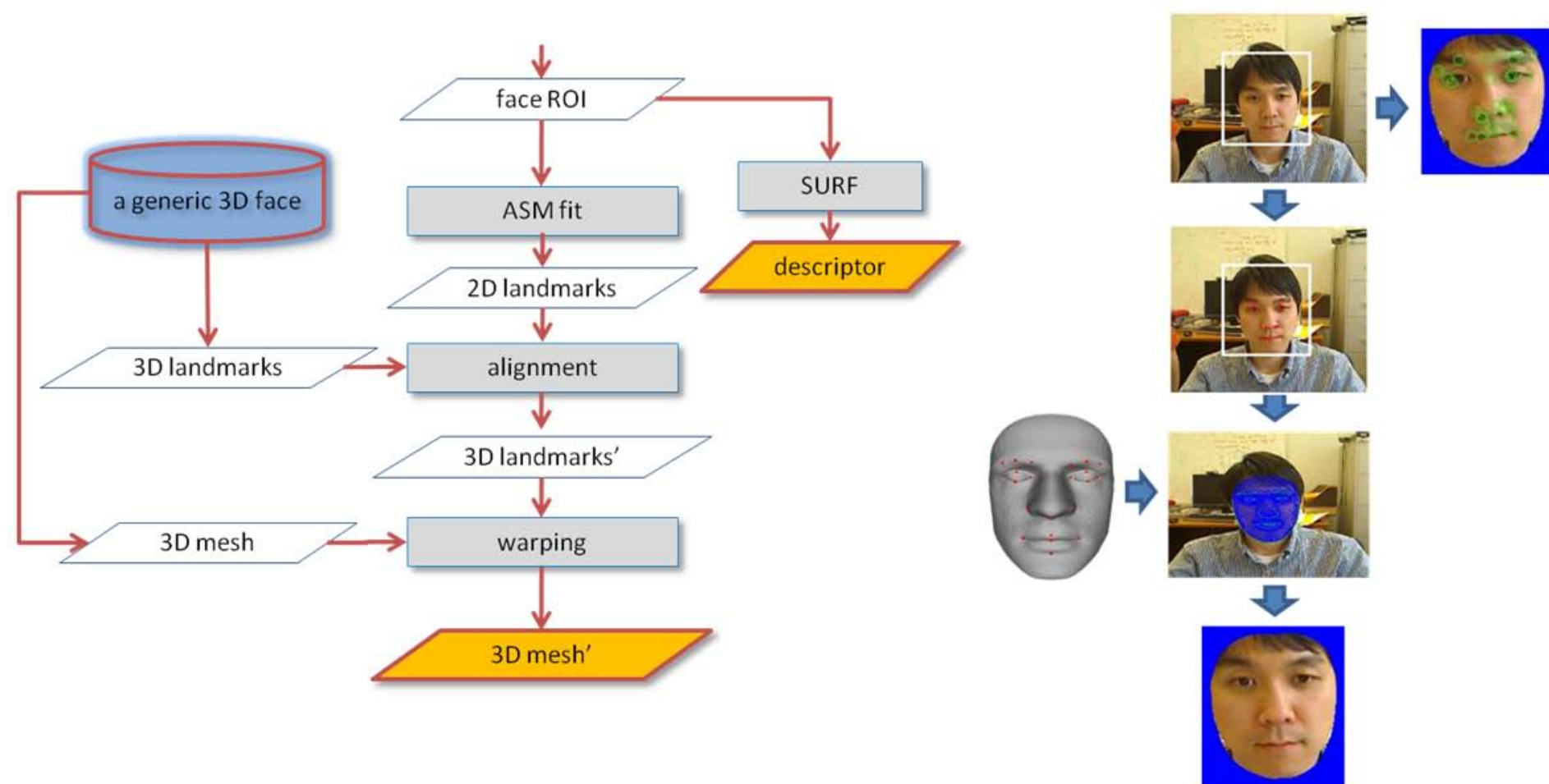
Re-acquisition

- Reacquisition after tracking loss
- Using stored descriptors (SURF)

Proposed Method

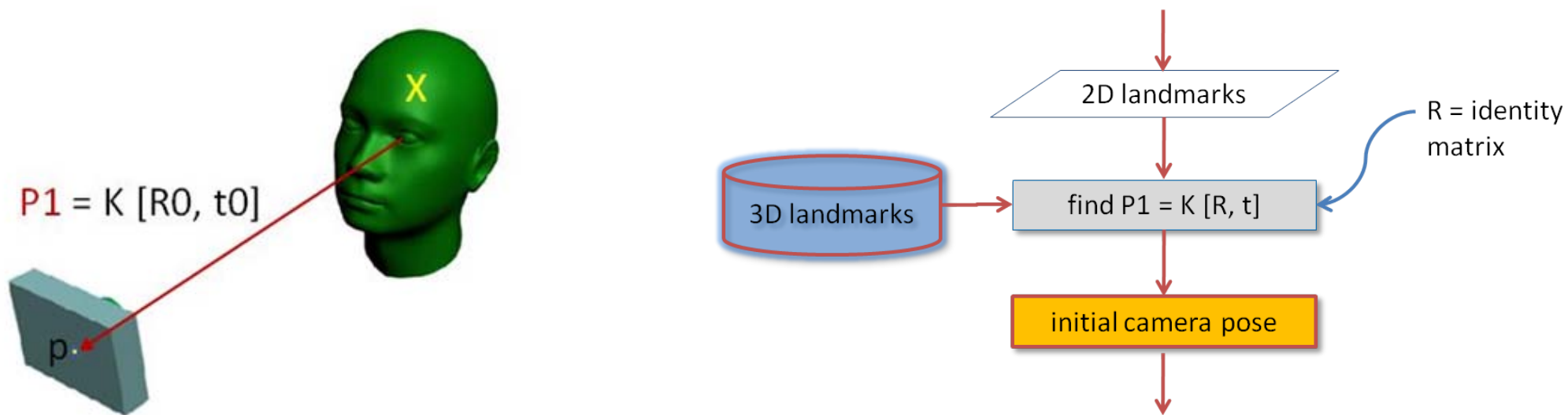
Initial 3D modeling

- ASM fit to 2D facial landmarks
- Warp 3D generic face model



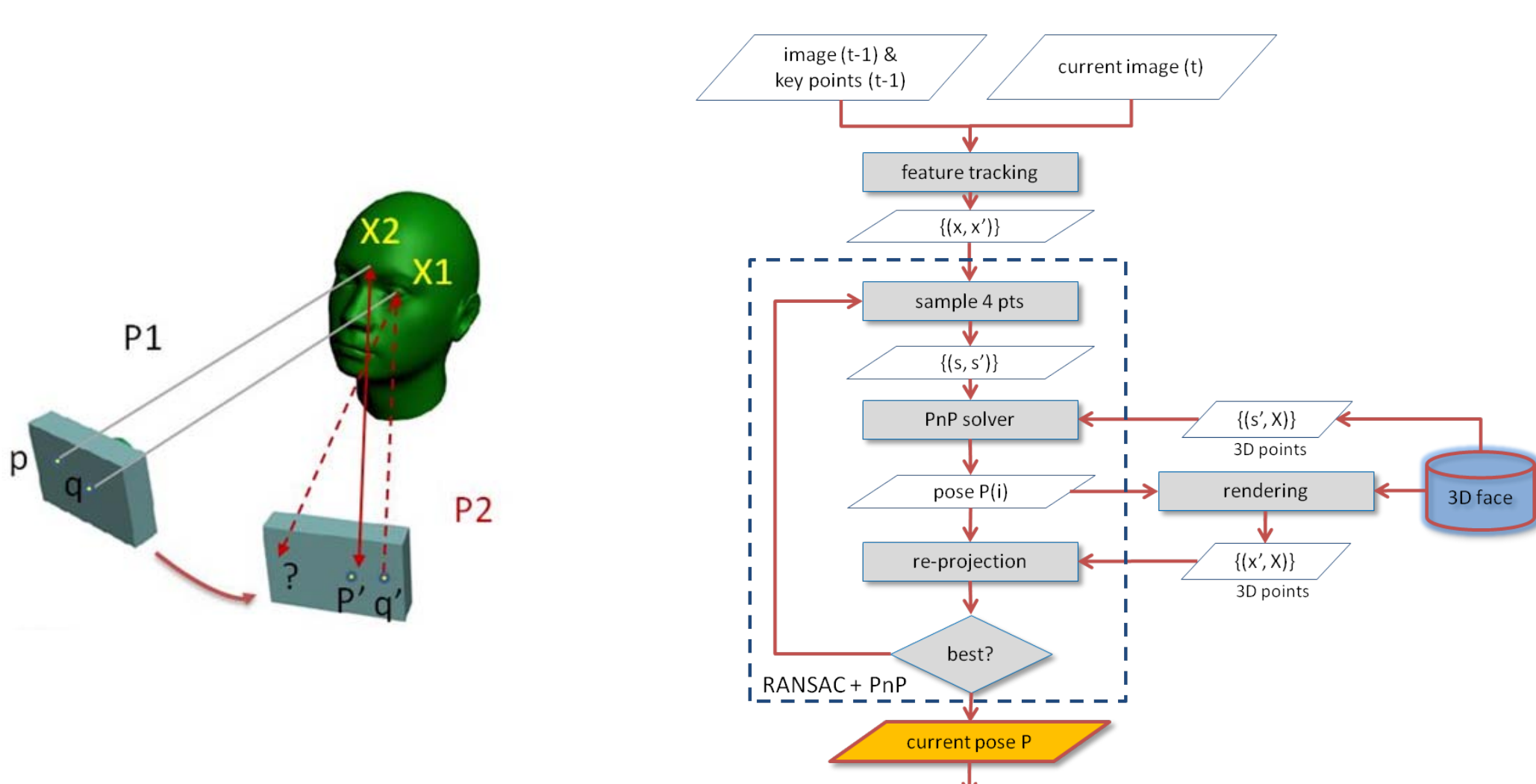
3D pose from tracked keypoints

- Initialization



3D pose using RANSAC + PnP method

- 2D tracking followed by 3D computation (RANSAC + PnP)



Experiments

- From videos and live input

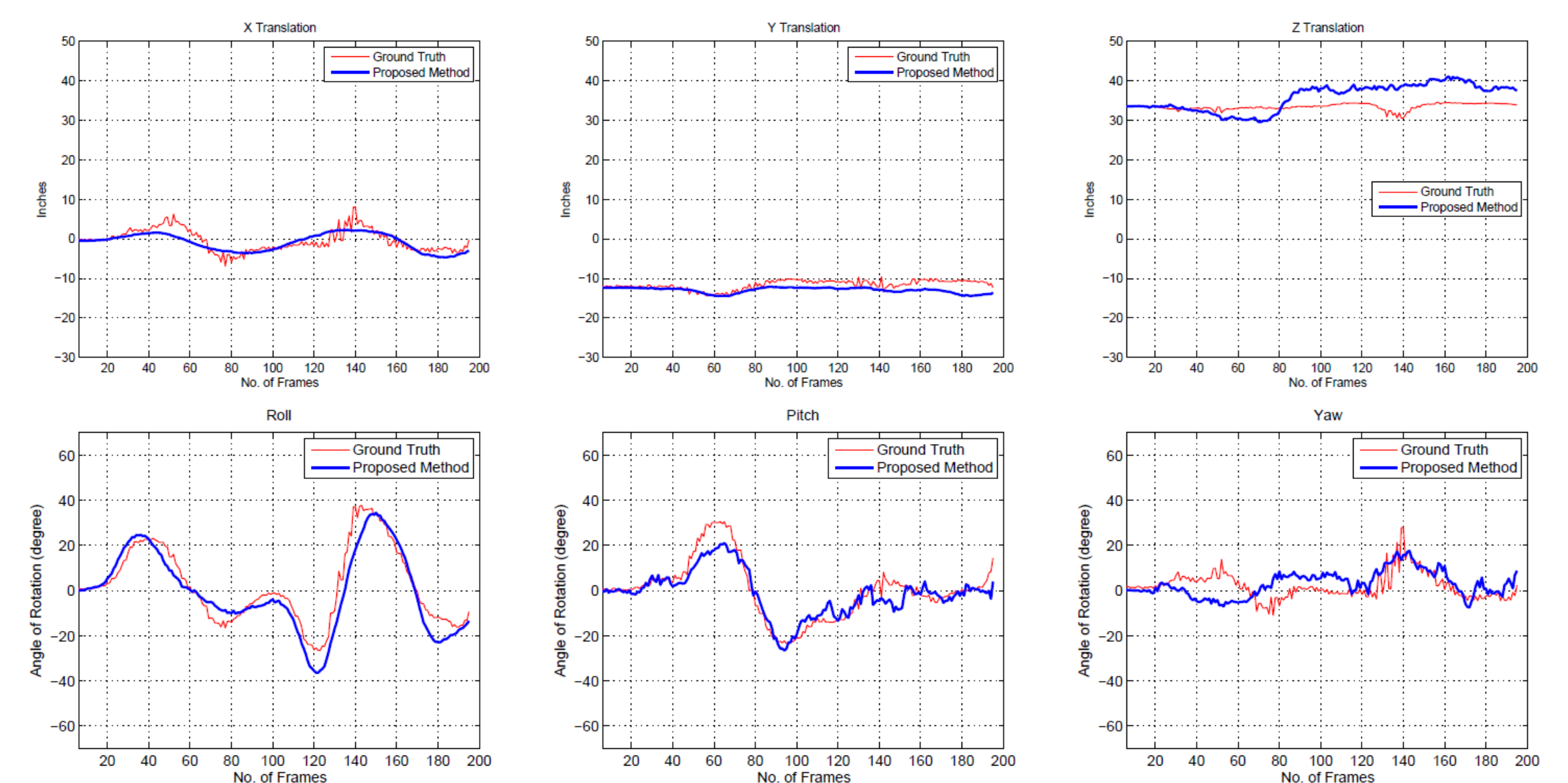


fast motion



rotation (pitch)

- From videos and live input



Conclusion and Future Work

- Real-time, accurate, robust 3D face tracking
- Pros and cons

(+)

- Robust and fast, real-time (>15Hz)
- Range (X: $\pm 70^\circ$, Y: $\pm 90^\circ$, Z: 360°)
- Distance (~1.8m, 30 pixels between eyes)
- Robust to facial expression changes

(-)

- Computation (GPU-SURF, rendering, ...)