

Towards m-Traveling Salesmen Problem in Time-dependent Road Networks



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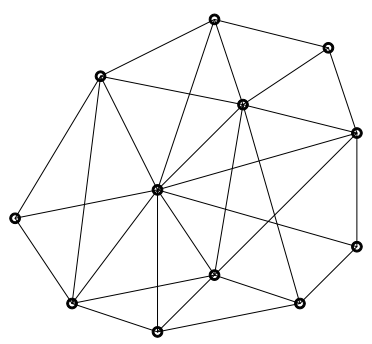
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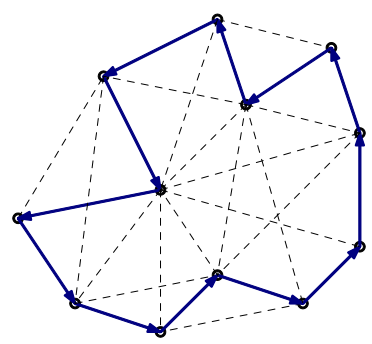
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Introduction

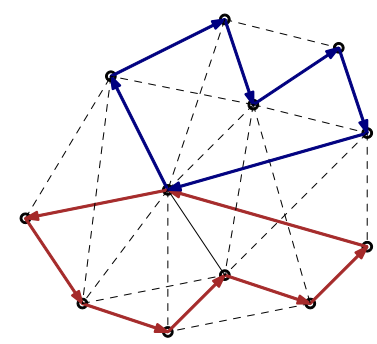
- **Traveling Salesman Problem (TSP)**: Given a set of cities and their pairwise distances, find the shortest possible route for a salesman such that each city is visited exactly once and finally returns to origin.
- **m-Traveling Salesman Problem (m-TSP)** is an extension of TSP where multiple salesmen are involved.
 - Each node is visited by at least one salesman;
 - The total traveling time of each salesman is $\leq h$, where h is a pre-defined parameter



Road network



TSP



m-TSP

Related Work

- **Time-dependent shortest path computation**
 - First solved by Dreyfus (JOR'69) with a variant of Dijkstra's algorithm.
 - First attempt on time-dependent k-NN query processing: Demiryurek et al, (DEXA'10).
- **Traveling salesman problem**
 - First defined in 1800s by mathematicians W. R. Hamilton and Thomas Kirkman.
 - First approximation algorithm proposed by Christofides, H. (1976) where the approximation ratio is upper bounded by 1.5.

Algorithm

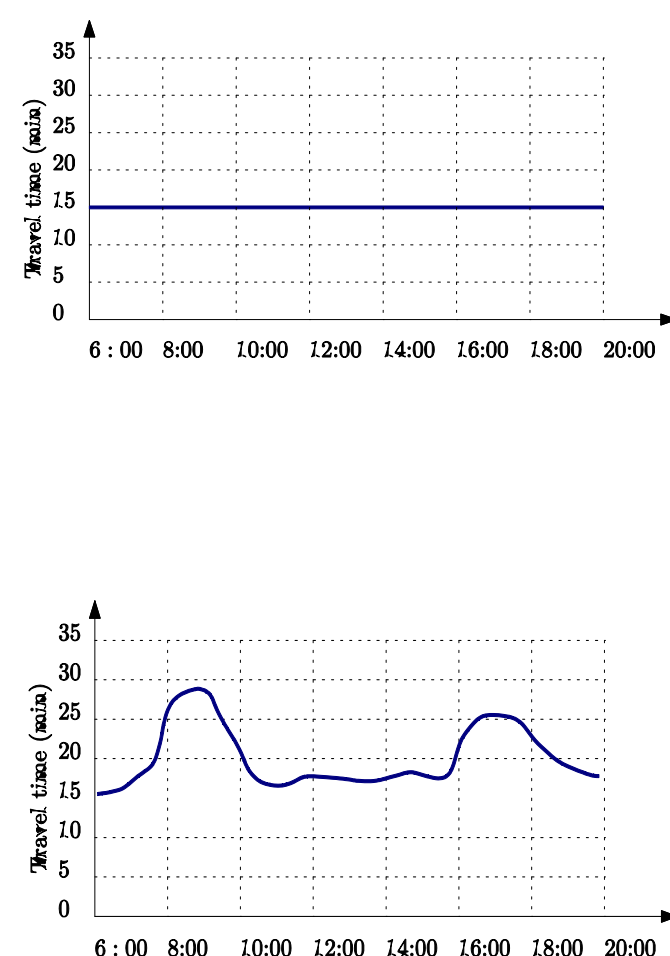
- Due to the NP-hardness of time-dependent m-TSP, we focus on an **approximation** solution using greedy approach.

Algorithm: m_TSP(G, C, c_0)
Input: Road network $G(V, E)$. Delivery centers $C \subseteq V$. Origin $c_0 \in C$.
Output: S , a set of salesmen with their routes.
 1: $S \leftarrow \{\}$;
 2: while C is not empty;
 3: add_salesman(S, C, c_0);
 4: return S ;

Algorithm: add_salesman(S, C, c_0)
Input: S a set of salesmen. C a set of delivery centers. Origin c_0 .
Output: null.
 1: $s \leftarrow$ a salesman and his route $r \leftarrow \{c_0\}$;
 2: $c \leftarrow$ the closest delivery center to c_0 in C ;
 3: while c can be added to r without violating time constraint
 4: $r \leftarrow r \cup$ the path from c_0 to c ;
 5: $C \leftarrow C - \{c\}$;
 6: $c \leftarrow$ the closest delivery center to c in C ;
 7: $s \leftarrow S \cup \{s\}$;

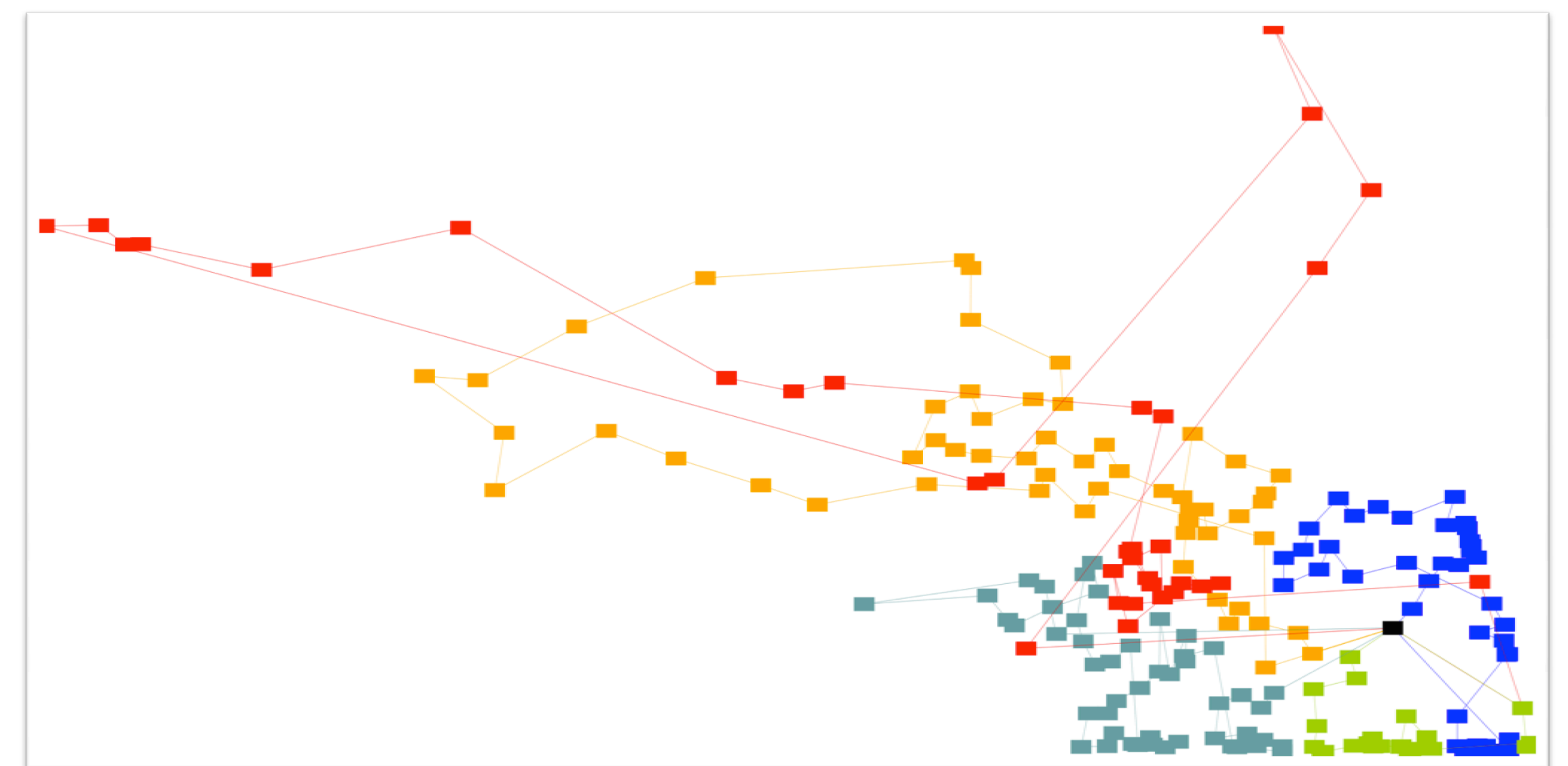
Time-dependent m-TSP

- Time-dependent m-TSP is a variant of m-TSP in the sense that optimal routes are computed in the context of a **time-dependent road network** instead of a static road network.
 - A time-dependent road network is a road network where the traveling time of the road segments varies with time.



Experiments

- **Dataset**
 - Los Angeles road network with $\sim 1.5 \times 10^5$ nodes and 258 delivery centers.
 - Time-dependent edge travel-times are generated based two-years of historical data collected from 6300 traffic sensors. The sampling rate of the data is 1 reading/sensor/min.
- **Evaluation**
 - How much total transportation time is saved (hours) by time-dependent shortest path planning compared with traditional shortest path planning.
 - Average time for computing delivery routes: **~ 150 seconds**.
 - Experiments show that in average we need **$\sim 1-2$ less** drivers to cover all LA delivery centers by using time-dependent route planning instead of static route planning.



Challenges

- m-TSP is an NP-hard problem, which derives directly from the NP-hardness of TSP.
- Difficult to find a solution to an NP-hard problem that is both **optimal** and **efficient**.
- Challenges also arise from time-dependency:
 - **Unpredictability of future traffic condition**. We solve this problem was solved by analyzing historical traffic information and using this knowledge to predict future traffic data.
 - **Expanded search space**. Since the time dimension is added to shortest path computing, we will have a much larger search space. It was proved that there might be an exponential number of shortest paths when traffic condition changes with time (Foschini et al, SODA'11).
 - **Existence of multiple shortest paths**. The shortest path also depends on the departure time from the source.

Problem size	50	60	70
Easy problem	0.0025 seconds	0.0036 seconds	0.0049 seconds
NP-hard problem	3855 centuries	2×10^8 centuries	∞

Conclusion

- Time-dependent m-TSP is a variant of m-TSP, where the traveling time depends on not only the distance but also the traffic condition of the roads that varies with time.
- Time-dependent m-TSP is more general and realistic approach than traditional m-TSP; time-dependent route planning saves **~ 25.9 hours'** total delivery time compared with static route planning that does not consider time dependency.
- m-TSP is NP-hard. It takes a intolerably long time to find the optimal routes. Therefore, we focus on approximate solutions using a greedy approach.