Traffic Prediction in Urban Road Networks - Comparison of Regressive Approach & Pattern Approach Bei (Penny) Pan, Ugur Demiryurek, Jingyi Du and Cyrus Shahabi **Integrated Media Systems Center University of Southern California IWatch** CT ✓ **ICampus** Introduction **Experiments** •Intelligent Transportation System (ITS) refers to information and Experimental Setup Spatial Coverage: 450 sensors from Los Angeles freeway communication technology that improves transportation outcome. Training data: Nov, 2011 / Testing data: first week in Dec, 2011 Data Resolution: 5-min •However, the benefits of ITS cannot be fully Forecasting interval: 30 minutes (i.e. M = 30 / 5 = 6 time stamps) TO J4A (FOR M42) realized if traffic is not "known" in 16 MILES Measures of effectiveness 18 MINS advance or forecasted. • MAPE (%) = $\frac{1}{n} \sum_{i=1}^{n} \frac{|y_i - \hat{y}_i|}{|y_i|} \times 100$ RMSE = $\sqrt{\frac{1}{n} \sum_{i=1}^{n} (y_i - \hat{y}_i)^2}$ •Effects of Hours in a Day (All Sensors, Wednesday) --- ARIMA — Pattern --- ARIMA — Pattern 30 30 25 25 ê²⁰ E 20



Related Work: Previous Efforts

•Regressive / Statistical Typical Approaches

- Auto-regressive integrated moving average (ARIMA)
- Exponential Smoothing (ES)
- Neural Network Models (NNet)
- Non-parametric Regression (NPR)

Limitation: lack of domain knowledge (e.g., people travelling behavior)

•Other Approaches

Historical Average Models

Limitation: no way to react to dynamic changes, such as events

Forecasting Problem & Approaches

Problem Formulation

- Input: speed time series (i.e., {y_i} 1 <= i<= N)
- Output: future speed values in M time stamps.
 i.e., {y_k} (N+1<=k <=N+M)

Regressive Solution

ARIMA Model

 $y_{t} = \sum_{k=1}^{\nu} \phi_{k} \bullet y_{t-k} + \sum_{k=1}^{\nu} \theta_{k} \bullet \varepsilon_{t-k} + \varepsilon_{t}$





•Observations:

1) Rush hour congestion makes prediction harder
2) Pattern approach is better when there is free flow traffic

•Effects of Days in a Week (All Sensors, All hours)



 Observations: 1) ARIMA approach provides better prediction during weekdays, because weekday data takes a larger portion of the training data.
 2) Pattern approach is better when it comes to weekend

•Effects of Location



- Key Features:
 - Models the relationship between current variable with previous variables & noise.
 - Only predicts 1 variable ahead, and accuracy may decrease if use predicted values as known values

Pattern Solution

- Pattern: daily speed sequence (itself is used as predicted value).
- Key Features:
 - Patterns are integrated with people traveling behavior, e.g., people go to work Mon-Fri, do not go to work at weekends.
 - Patterns filter out all the noises, so it is incapable of predict events.



- Pattern Categories:
- Regular: Mon~Sun
- Long Weekend: Fri~Tue
- Thanks Giving: Wed~Mon
- Special Event: Sat, Sun

Observations:

 ARIMA approach provides better prediction for specific regions or freeways, for example, downtown area, I-10, I-605.
 Pattern approach is better when it comes to less-event area, where traffic mostly follows the cyclical nature.

Conclusion & Future Work

•Conclusion

• This study empirically compares the pros & cons of regressive approach and pattern approach on traffic prediction problem.

•Future work

- Introduce domain knowledge while training the regressive model.
- Enrich the pattern categories with event/accident pattern etc.



